

FIG. 1

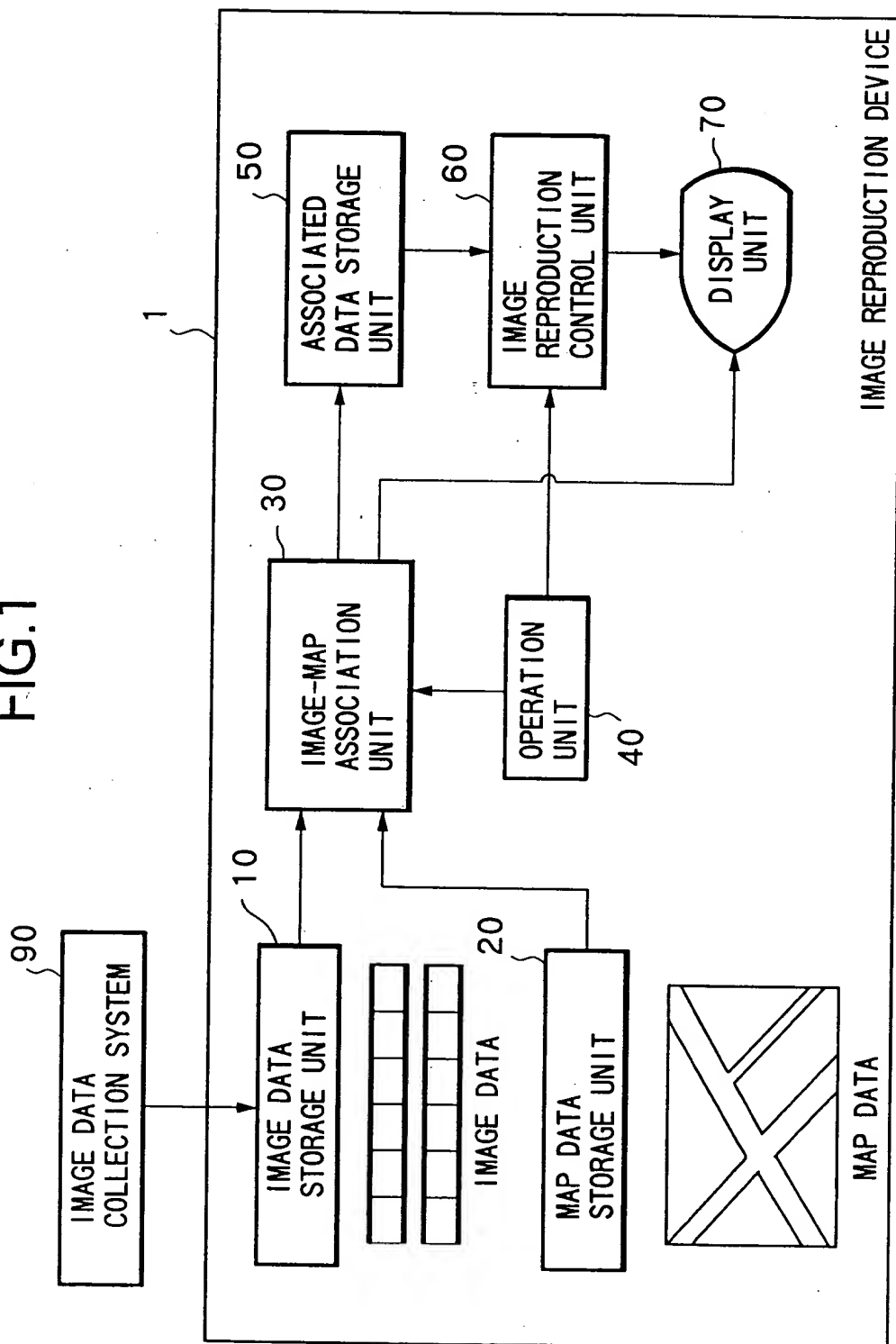


FIG.2

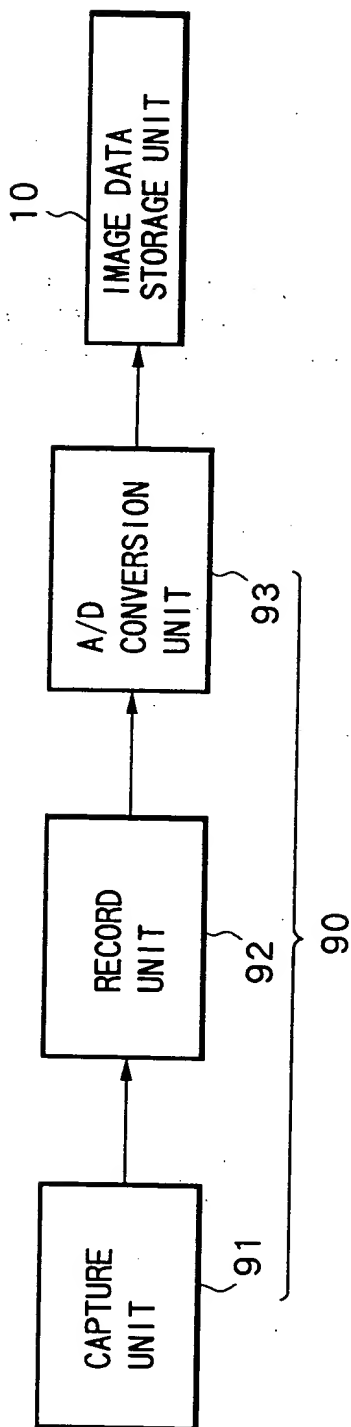


FIG.3

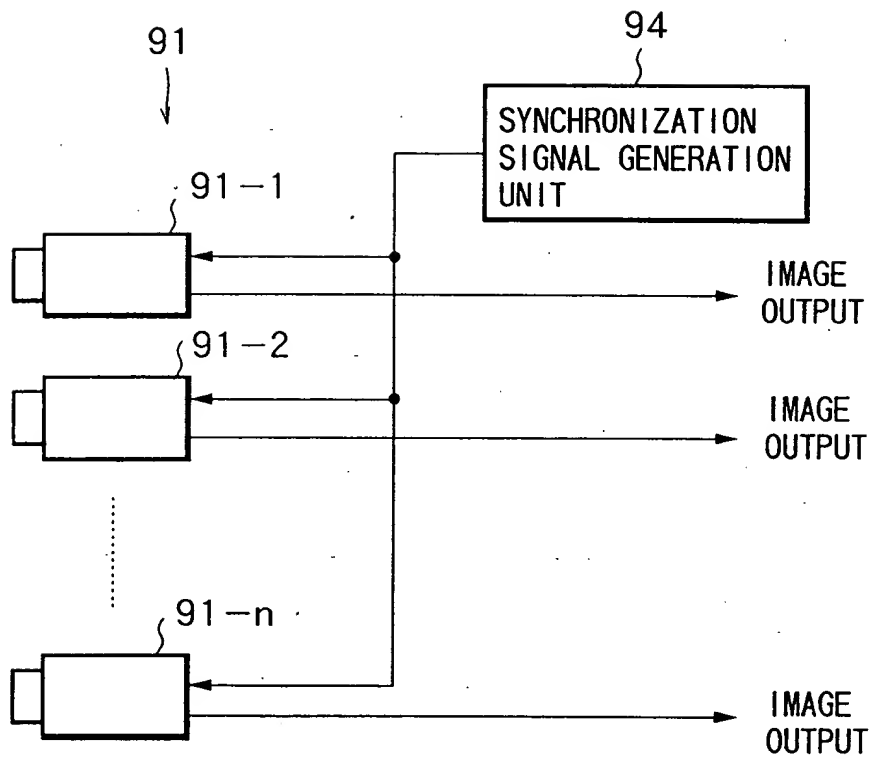


FIG.4

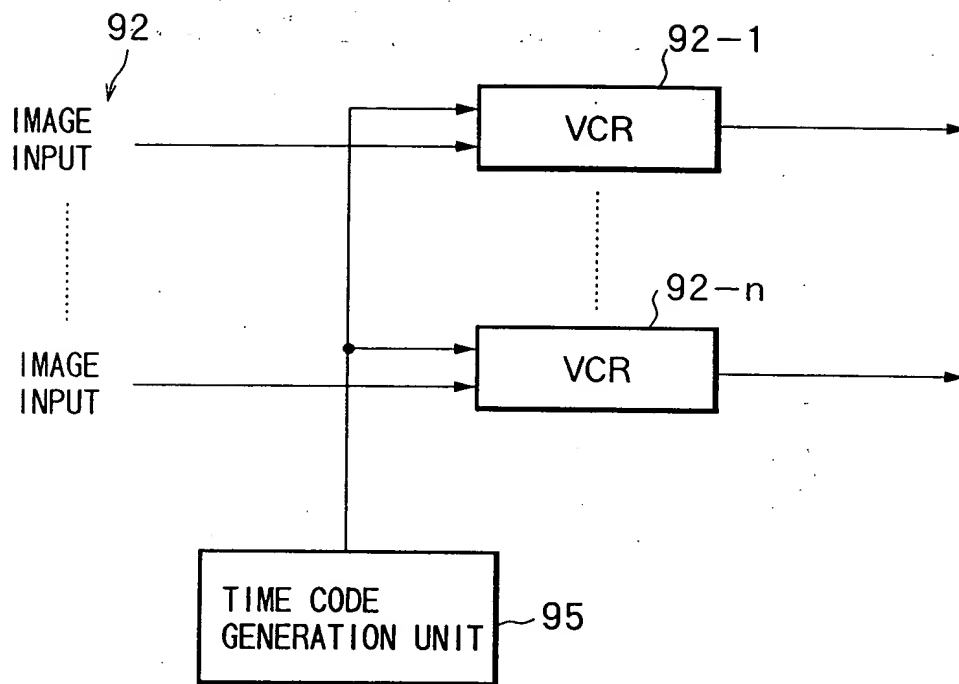


FIG.5

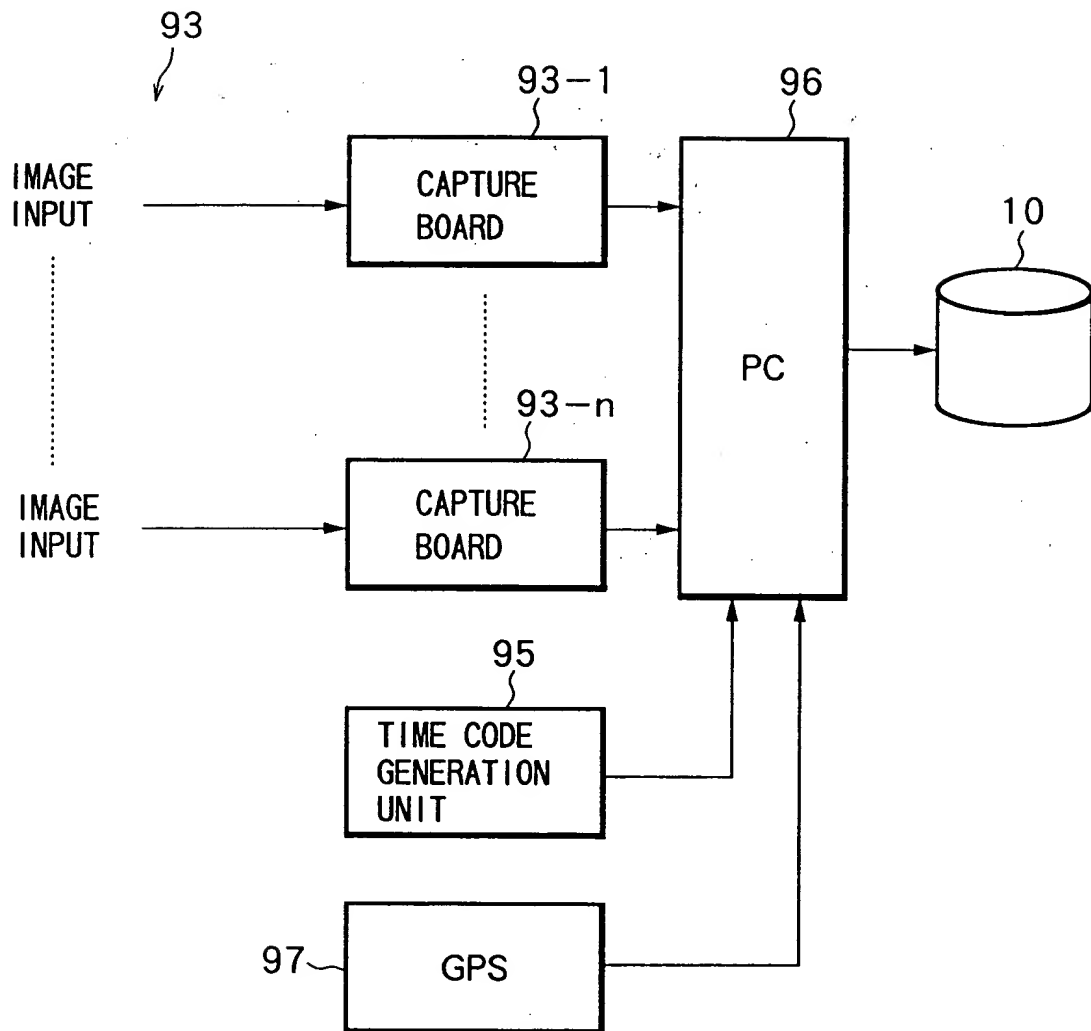


FIG.6

## POSITION DATA (GPS MEASUREMENT RESULT DATA)

TIME CODE	POSITION( $\theta$ )	POSITION( $\phi$ )
00:00:00:01	135.000	35.000
00:00:00:02	135.002	35.001
00:00:00:03	135.004	35.002
00:00:00:04	135.005	35.002
...	...	...
00:00:00:10	135.010	35.008

## VIDEO DATA

TIME CODE	FRAME NUMBER	FRAME DATA
00:00:00:01	000001	
00:00:00:02	000002	
00:00:00:03	000003	
00:00:00:04	000004	
:	:	
00:00:00:10	000010	

00:00:00:01  
00:00:00:02  
00:00:00:03  
00:00:00:04  
00:00:00:05  
00:00:00:06  
00:00:00:07  
00:00:00:08  
00:00:00:09  
00:00:00:10

FIG. 7

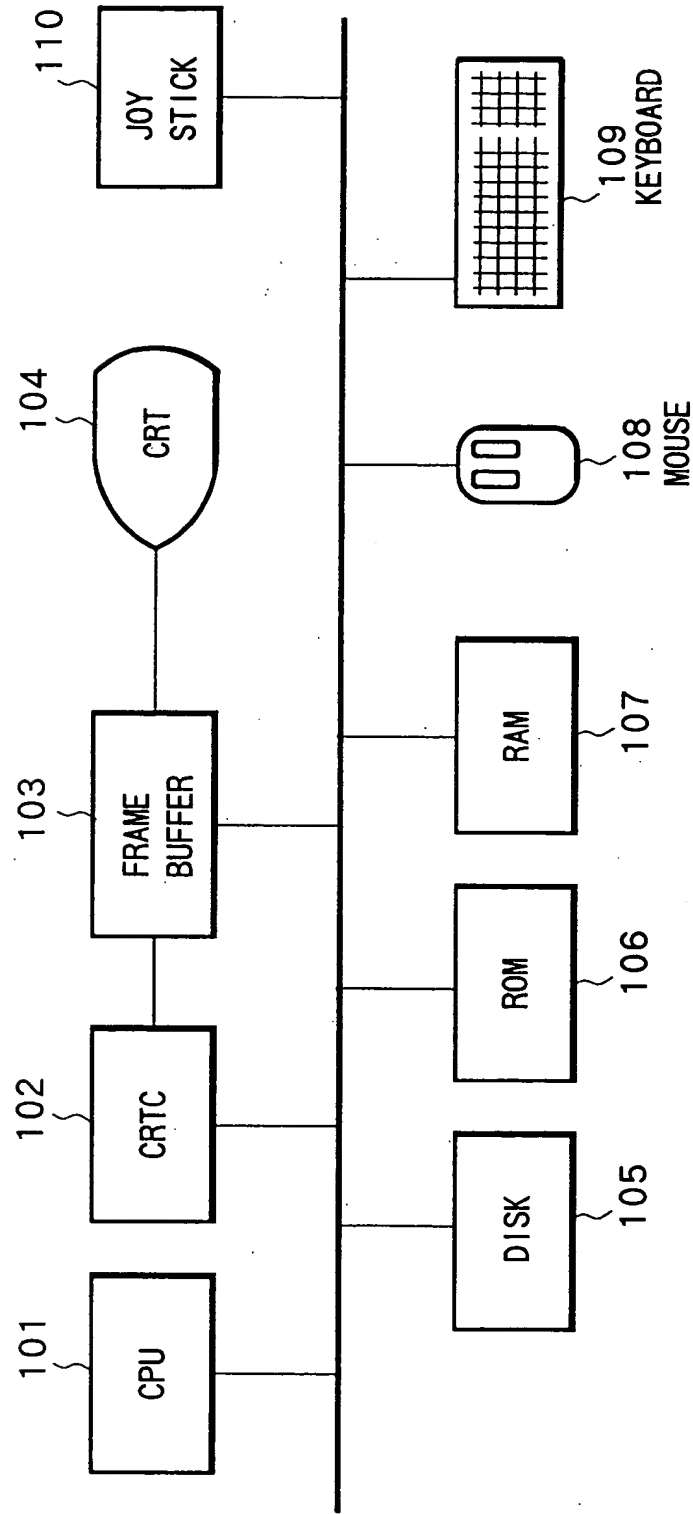


FIG.8

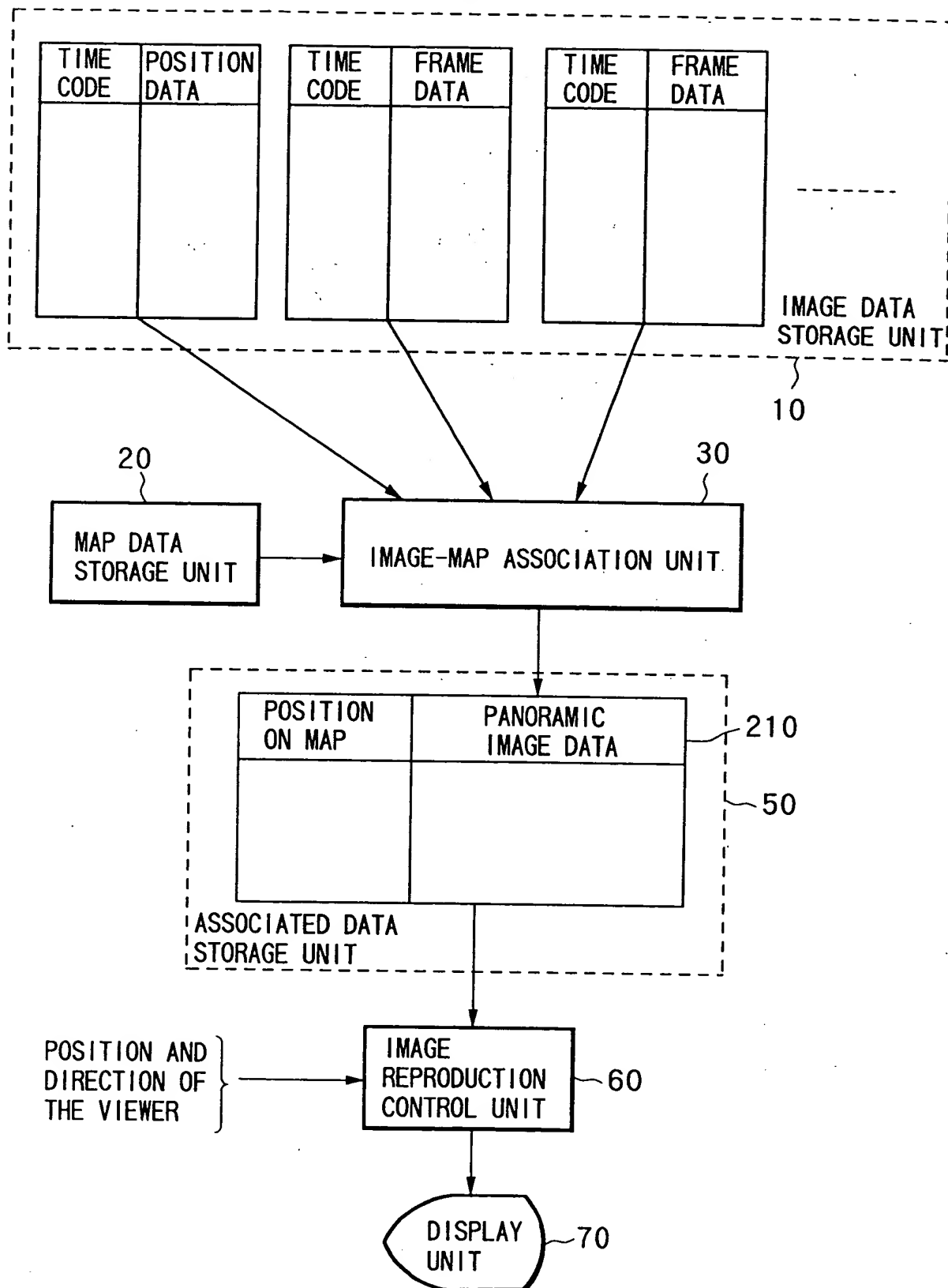




FIG.9

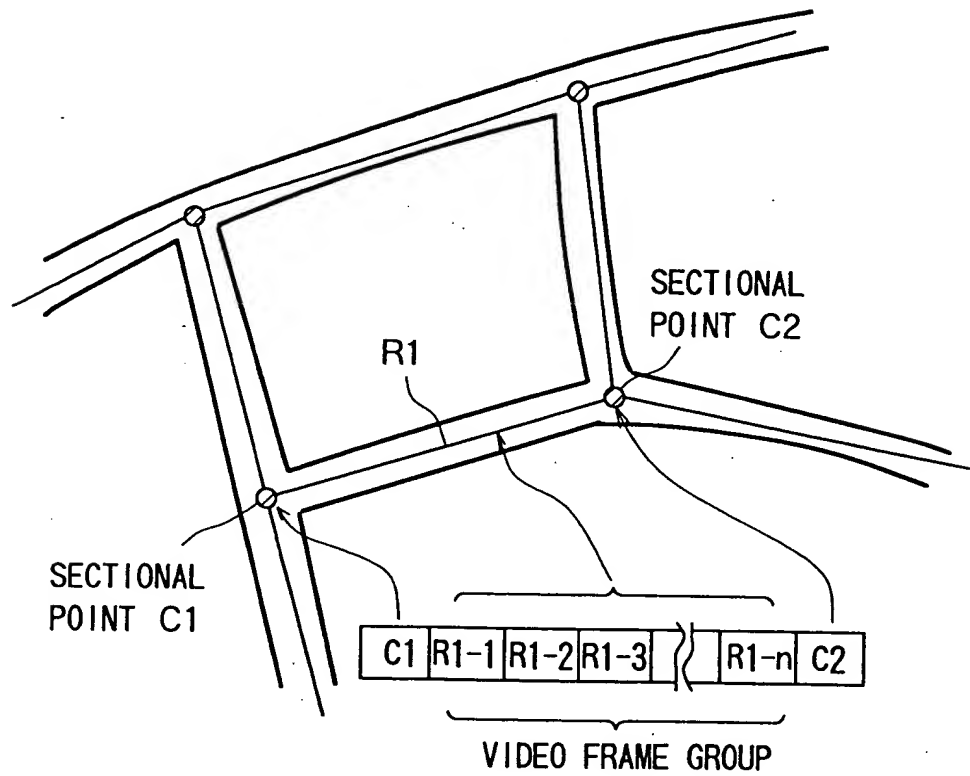


FIG.10

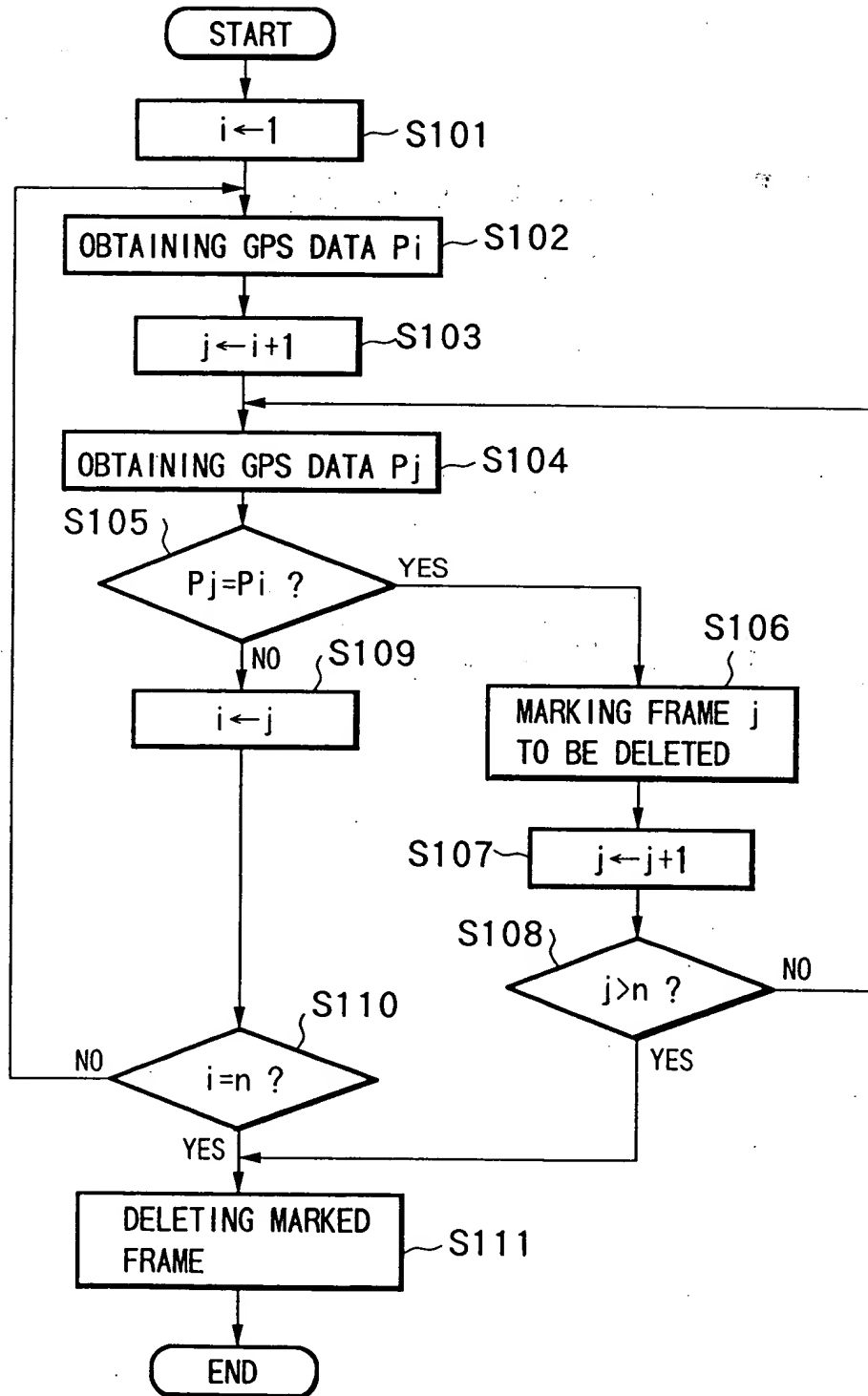


FIG.11

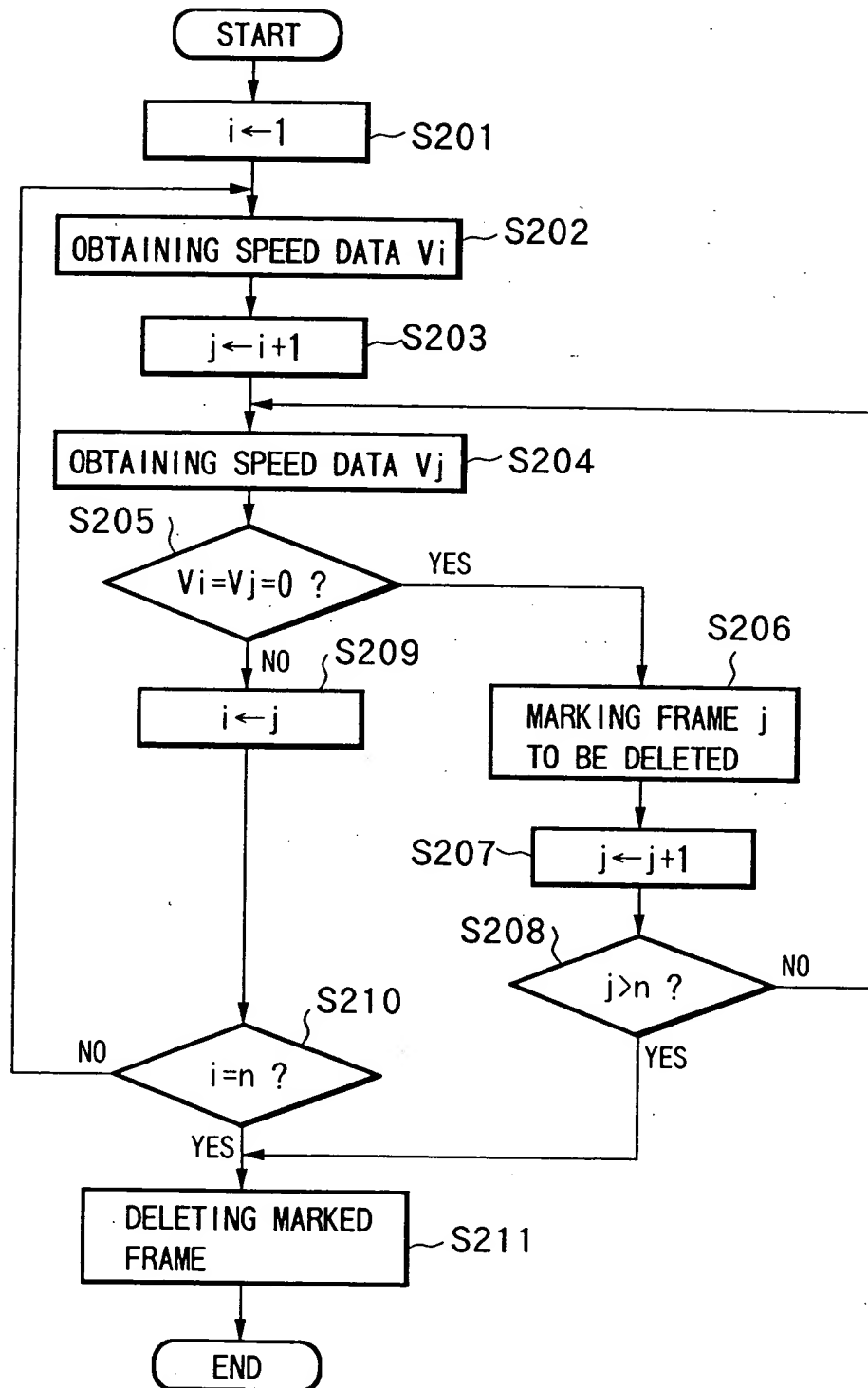


FIG.12

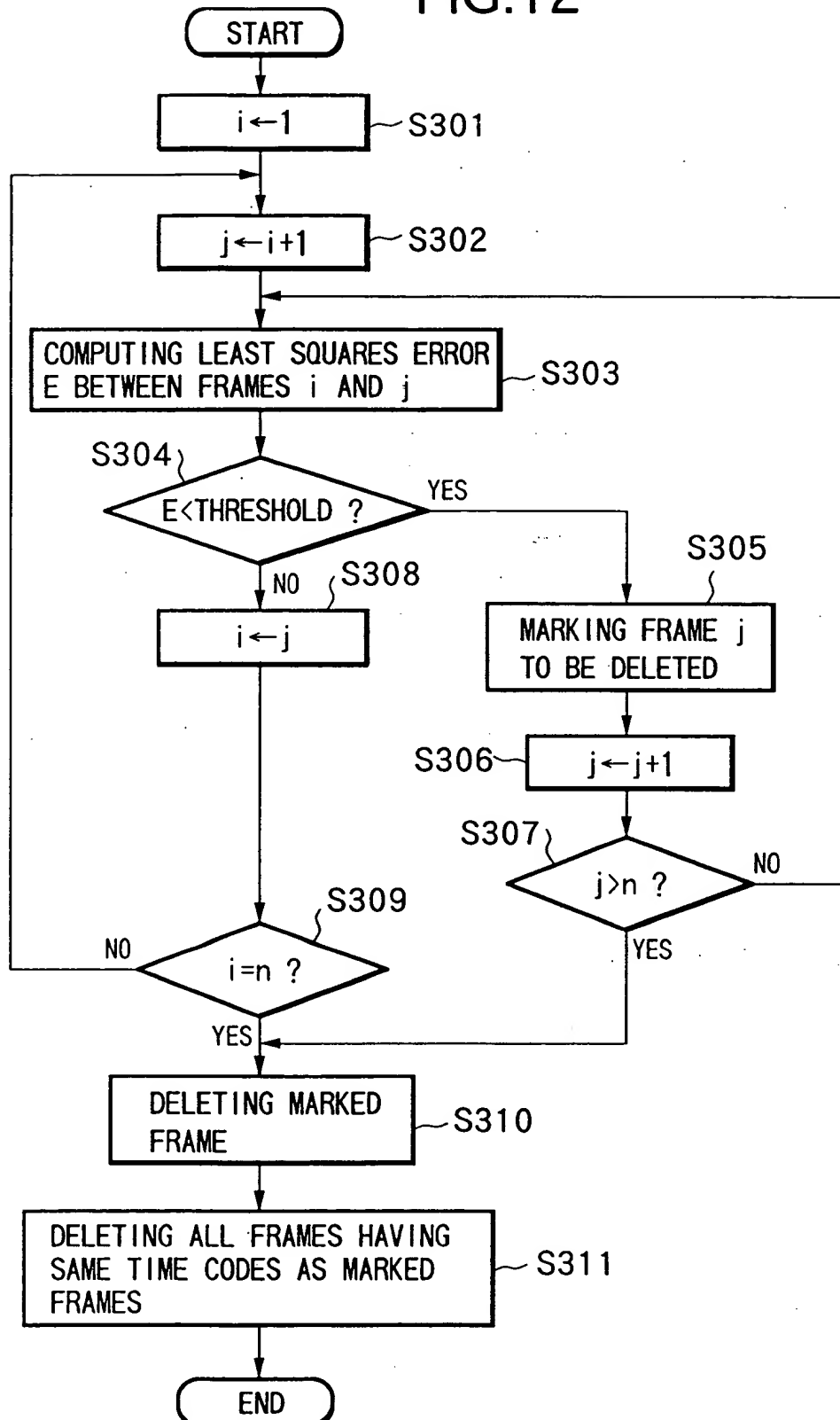


FIG.13

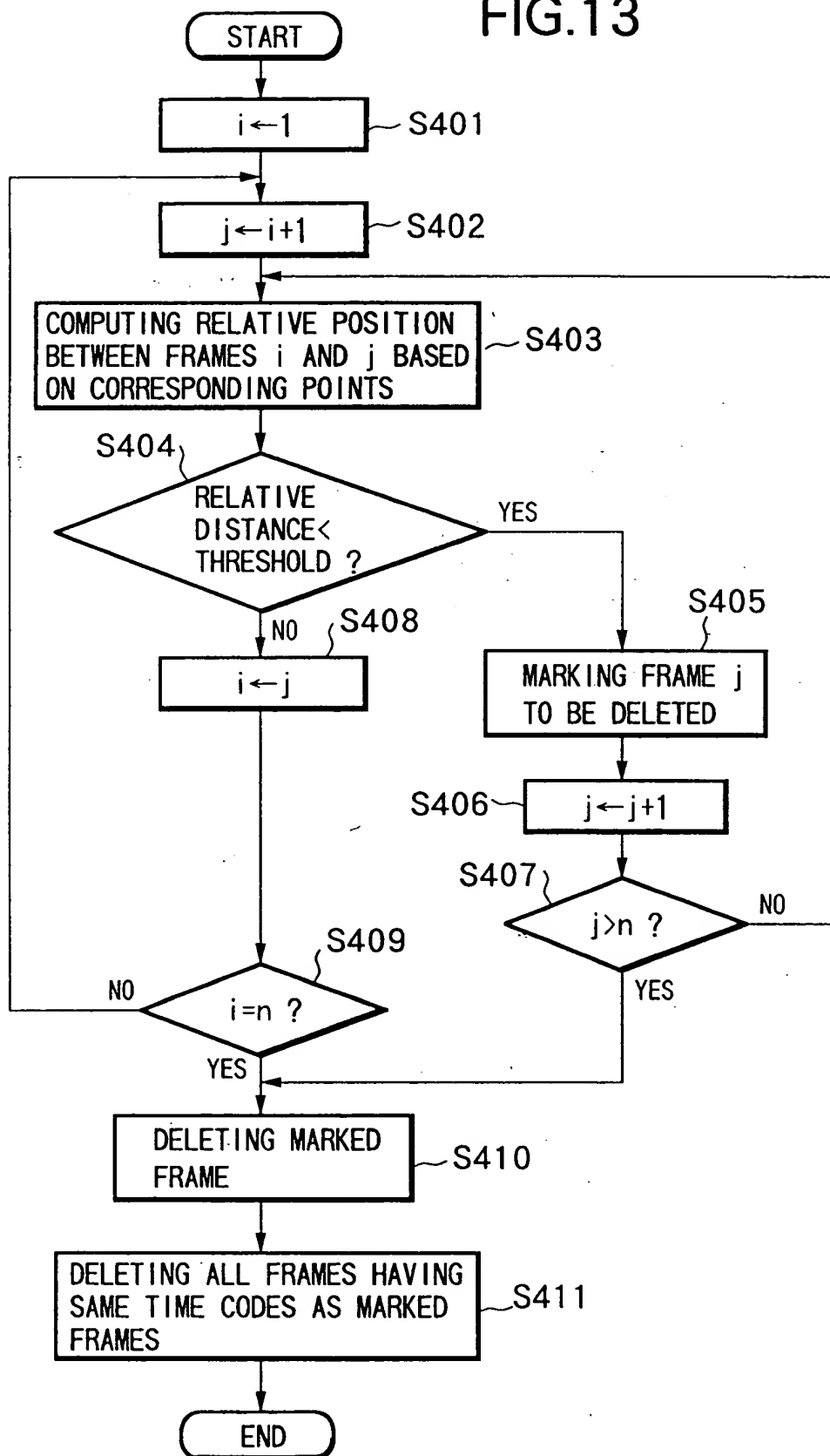


FIG.14

